

IN THE NAME OF ALLAH,

MOST GRACIOUS, MOST MERCIFUL



INTRODUCTION TO NUMERICAL METHODS WITH APPLICATION TO CHEMICAL ENGINEERING

Emad Ali AbdelHamid Ajbar Khalid Alhumaizi

Department of Chemical Engineering College of Engineering King Saud Univesity Riyadh, Saudi Arabia



© King Saud University, 2009

King Fahd National Library Cataloging-in-Publication Data

Ali, Emad

Introduction to numerical methods with application to chemical engineering. / Emad Ali; AbdelHamid Ajbar; Khalid Alhumaizi. - Riyadh, 2008

272 p., 17 x 24 cm ISBN: 978-9960-55-394-8

1-Chemical engineering I-AbdelHamid Ajbar (co. author) II-Khalid Alhumaizi (co. author) III-Title

660.2 dc 1429/6033

Legal Deposit No. 1429/6033 ISBN: 978-9960-55-394-8

This book has been refereed by a specialized committee appointed by the Academic Council of the University. After the reports of the referees, the Council authorized its publication in its 5th session of the academic year 1428/1429 H., which was convened on 21-11-1428 H. (1-12-2007)



PREFACE

Many chemical engineering departments in diverse universities around the world, including the one in King Saud University, include in the curriculum a course designed to teach numerical methods applied to chemical engineering. This book is essentially a compilation of the notes the three authors have used to teach this course over the years. We have covered in the textbook the numerical techniques that are most useful to the chemical engineer and that have wide applications. As an introduction to the book, we included a chapter dealing with some practical considerations in numerical methods. The concepts of errors, conditioning of a problem and stability of algorithms were introduced to show the student to what extent he should trust any numerical values obtained by solving a problem in a digital computer. The first type of problems covered by the book is the system of linear algebraic equations (Chapter 2). This choice is in line with the contents of the prerequisite of the course that teaches numerical solutions of mass and energy balance equations. Many linear algebraic equations originate from the applications of steady state mass balance equations. The chapter that follows deals with the solution of non-linear algebraic equations. Chapter 3 is a normal continuation to the previous chapter since many applications of non-linear algebraic equations originate from steady state energy balance equations. Chapters 4 and 5 deal with the solution of ordinary differential equations, initial value problem and boundary value problem, respectively. Students are introduced to numerical solutions of unsteady state mass and energy balance equations as well as to numerical solutions of steady state one dimensional distributed parameter models. The rest of the book (Chapters 6 to 10) deal with the issue of optimization. This issue is divided in three parts. The first part (Chapter 6) deals with linear regression. We choose to start by linear regression (simple and generalized) since it is a subject that has direct applications in other students courses, especially in students labs experiments. Also, the numerical methods for linear regression are essentially those of linear algebraic equations that were covered in Chapter 2. The second part of optimization is divided into three chapters (Chapter 7, 8 and 9). Chapter 7 introduces the students to basic concepts of single variable optimization, and presents some numerical methods. Chapter 8 generalizes the concepts of Chapter 7 to multivariable unconstrained problems. It also provides a number of numerical techniques for these types of problems. Chapter 9 deals with the constrained optimization problems where the Lagrange multipliers method is introduced. The last part of the optimization issue is covered in Chapter 10 where linear programming is taught in detail.

The various numerical methods were presented in the form of flow-chart diagrams. Each numerical method introduced in the text has a solved example associated with it. Virtually, all the examples are chemical engineering problems, spanning wide areas from mass and energy balance equations to kinetics and thermodynamics. The programming language used to teach this book is FORTRAN, and we also rely on IMSL routines. These routines are in many cases sophisticated and are based on special implementation of the basic methods taught in the body of the book. For these reasons, we have introduced at the end of each chapter two sections: a section entitled "Other Solution Techniques". In this section, the students are introduced very briefly to other more elaborate solution techniques, but the objective of this section is also to introduce the students to the special methods and algorithms that are effectively used in the IMSL routines. The second section at the end of the chapter presents some IMSL routines that were commonly used in the teaching of the materials. In addition to all of this, we have presented at the end of the book a collection of FORTRAN programs that can be used directly (without the need for IMSL routines) to solve some basic problems covered in the chapter.

The text is designed primarily for undergraduate students who have knowledge of the fundamentals of chemical engineering and some background in calculus especially linear algebra and differential equations. However, some parts of the book could also be used as part of a first year graduate course on numerical methods. For undergraduate level, the materials that could be used for a 15-week long semester could include:

- Chapter 1: Basic concepts on errors, conditioning and stability.
- Chapter 2: Solution of linear systems. Cuts could be made depending on the materials taught in the prerequisite of the course. For instance, in the chemical engineering department at KSU, a prerequisite course teaches students the fundamentals of Gauss elimination methods. The instructor could focus on LU decomposition and on iterative methods.
- Chapter 3: Non-linear systems. Secant and Müller method could be skipped or assigned as student review.
- Chapter 4: Solution of ODE-initially value problem could be covered in full.
- Chapter 5: Boundary value problem could also be covered in full.
- Chapter 6: Linear regression could be covered in full.
- Chapter 7: Single variable optimization could be covered in full.
- Chapter 8: Multivariable unconstrained optimization, Chapter 9: Multivariable constrained optimization, and Chapter 10: Linear programming are best left to another semester, if available. These chapters could also be taught as part of a first level graduate course.

CONTENTS

			Page
Preface			v
Chapter 1	: Practica	l Issues in Numerical Methods: Errors, Conditioning	
	and Stal	pility	1
1.1	Introduc	tion	1
1.2	Numeric	al Errors	1
	1.2.1	Errors Definitions	1
	1.2.2	Round-off Errors	2
	1.2.3	Truncation Errors	3
1.3	Conditio	ning of a Problem	4
1.4	Stability	of an Algorithm	6
1.5	Problem		9
Chapter 2	: System o	of Linear Equations	11
2.1	Introduc	tion	11
2.2	Basic Co	oncepts of Matrix Algebra	13
	2.2.1	Definitions	13
	2.2.2	Matrix and Vector Norms	16
	2.2.3	Condition Number of a Matrix	17
2.3	Introduc	tion to Direct Methods	19
2.4	Special 7	Types of Systems	19
	2.4.1	Diagonal System	19
	2.4.2	Lower Triangular System	21
	2.4.3	Upper Triangular System	
2.5		the General Case System by LU Factorization	
	2.5.1	LU Factorization	25

		2.5.2	Operation Counts	30
		2.5.3	Computing the Determinant and the Inverse	30
	2.6	Gauss-Jos	rdan Elimination Methods	30
		2.6.1	Gauss Elimination with No Pivoting	31
		2.6.2	Gauss-Jordan Elimination with Partial Pivoting	33
		2.6.3	Gauss Elimination with Scaled-column Pivoting	34
		2.6.4	Operation Counts	36
	2.7	Introduct	ion to Iterative Methods	36
		2.7.1	Selection of the Splitting Matrix	37
	2.8	Jacobi M	ethod	38
	2.9	Gauss-Sie	edel Method	40
	2.10	Other Sol	ution Techniques	41
	2.11	IMSL Ro	utines	45
	2.12	Problems		46
Cha	pter 3:	Non-line	ar Algebraic Equations	55
	3.1	Introduct	ion	55
	3.2	Single Va	ariable Equation	58
		3.2.1	Fixed-point Iteration	58
		3.2.2	Bisection Method	62
		3.2.3	Newton-Raphson Method	69
		3.2.4	Secant Method	73
	3.3	System of	f Non-linear Equations	76
		3.3.1	Newton's Method for System of Non-linear Algebraic	
			Equations	76
	3.4	Zeros of l	Polynomials	81
		3.4.1	Müller's Method	82
	3.5	Other Sol	ution Methods	85
	3.6	IMSL Ro	utines	85
	3.7	Problems		86
Cha	pter 4:	Ordinary	Differential Equations: Initial Value Problem	95
	4.1	Introduct	ion	95

4.2	First Order ODE	99
	4.2.1 Taylor Series Expansion	100
	4.2.2 Truncation Errors	100
	4.2.3 Explicit Euler's Method	101
	4.2.4 Runge-Kutta Method of Second Order	104
	4.2.5 Fourth Order Runge-Kutta	107
	4.2.6 Runge-Kutta with Adaptive Step Size	109
	4.2.7 Implicit Euler's Method	110
4.3	System of Coupled ODES	112
	4.3.1 Euler's Method for the System of Coupled ODEs	113
	4.3.2 Fourth Order Runge-Kutta Method for the System of	
	Coupled ODEs	115
4.4	Stability of the Integration Methods	117
4.5	Stiff Differential Equations	120
4.6	Other Solution Techniques	121
4.7	IMSL Routines	122
4.8	Problems	123
Chapter 5:	: Differential Equations: Boundary Value Problem	133
Chapter 5: 5.1	: Differential Equations: Boundary Value Problem	133 133
-		
5.1	Introduction	133
5.1	Introduction Numerical Methods for the Solution of BVP Problems	133 136
5.1	Introduction Numerical Methods for the Solution of BVP Problems	133 136 136
5.1	Introduction Numerical Methods for the Solution of BVP Problems	133 136 136 142
5.1 5.2	Introduction Numerical Methods for the Solution of BVP Problems	133 136 136 142 146
5.1 5.2 5.3	Introduction Numerical Methods for the Solution of BVP Problems	133 136 136 142 146 148
5.1 5.2 5.3 5.4	Introduction Numerical Methods for the Solution of BVP Problems	133 136 136 142 146 148 149
5.1 5.2 5.3 5.4 5.5 5.6	Introduction Numerical Methods for the Solution of BVP Problems	133 136 136 142 146 148 149 150
5.1 5.2 5.3 5.4 5.5 5.6	Introduction Numerical Methods for the Solution of BVP Problems	133 136 136 142 146 148 149 150
5.1 5.2 5.3 5.4 5.5 5.6 Chapter 6:	Introduction Numerical Methods for the Solution of BVP Problems	133 136 136 142 146 148 149 150 151

	6.2.2	Application of L	inear Regression to Non-linear Models	164			
6.3	General Linear Least Squares Method						
	6.3.1 Application: Polynomial Regression						
6.4	Multiple Linear Regressions						
6.5	Other Solution Techniques						
6.6	IMSL R	outines		177			
6.7	Problem	s		178			
Chapter 7	: Optimi	zation: Single Vari	able Problems	183			
7.1	Introduc	tion		183			
7.2	Introduc	tion to Optimizatio	n of One Single Variable Function	184			
	7.2.1	Unimodal Functi	on	185			
	7.2.2	Convex Function	ıs	186			
	7.2.3	Optimality Cond	itions	186			
	7.2.4	Theorem		187			
7.3	Numeri	al Methods		188			
	7.3.1	Scanning and Br	acketing Procedures	189			
	7.3.2	Optimization Me	thods Requiring Derivatives	190			
	7.3.3	Region-eliminati	on Methods	190			
7.4	Other S	olution Techniques		195			
7.5	IMSL R	outines		196			
7.6	Problem	s		197			
Chapter 8	: Multidi	mensional Uncons	trained Problems	201			
8.1	Introduc	tion		201			
8.2	Unimod	al Functions		203			
8.3	Convex	Functions		203			
8.4	Optimal	ity Criteria		204			
8.5	Numeri	cal Techniques		207			
	8.5.1		ate Direction Method	209			
	8.5.2	Gradient Method		213			
	8.5.3	Newton's Method	1	216			
	8.5.4	Marquardt's Met	hod	218			

8.6	Other Sol	lution Tec	hni	ques			220
8.7	IMSL Ro	utines					221
8.8	Problems						222
Chapter	9: Cons	strained	M	Iultidimensional	Problems:	Lagrange	
	Mult	tipliers M	eth	10d			225
9.1	Introduct	ion					225
9.2	Lagrange	Multiplie	rs				225
9.3	Economic	c Interpret	atio	on of Lagrange Mu	ıltipliers		226
9.4	Lagrange	Multiplie	rs f	for Inequality Cons	straints		227
9.5	Other Sol	lution Tec	hni	ques			235
9.6	IMSL Ro	utines					236
9.7	Problems						237
Chapter 1	0: Linear l	Programı	nin	ng			241
10.1	Introduct	ion					241
10.2	Simplex 1	Method					242
	10.2.1	Problem	Fo	rmulation			242
	10.2.2	Graphica	al R	Representation			244
10.3	Simplex A	Algorithm	l				247
	10.3.1	First Ste	p				247
	10.3.2	Second S	Step	p			247
	10.3.3	Third St	ер				248
10.4	Special C	Cases					251
	10.4.1	Multiple	So	olutions			251
	10.4.2	Unbound	ded	Solution			252
	10.4.3	No Obvi	ous	s Feasible Solution	Exists		253
	10.4.4	Big M M	1 etl	nod			254
10.5	Revised S	Simplex M	l etl	nod			255
10.6	Sensitivit	y Analysi	s				258
	10.6.1	Changes	in	the Coefficients	of the Right	Hand Side	
		Vector					258

		10.6.2 Effect of C	Change in the Cost Function Coefficients	260
	10.7	Duality		261
	10.8	Other Solution Tech	niques	262
	10.9	IMSL Routines		262
	10.10	Problems		263
Refe	rences			265
Inde	X			269